

MPI Error Code Index 04.04.08

The following table provides a list of hexadecimal error codes and the corresponding return value.

Error Code	Return Value
0x0000 (0)	OK
0x0001 (1)	Argument invalid
0x0002 (2)	Parameter invalid
0x0003 (3)	Handle invalid
0x0004 (4)	Out of memory
0x0005 (5)	Object freed
0x0006 (6)	Object not enabled
0x0007 (7)	Object not found
0x0008 (8)	Object on list
0x0009 (9)	Object in use
0x000a (10)	Timeout
0x000b (11)	Unsupported
0x000c (12)	Fatal error
0x000d (13)	File close error
0x000e (14)	File open error
0x000f (15)	File read error
0x0010 (16)	File write error
0x0011 (17)	Firmware File Mismatch
0x0012 (18)	Assertion Failure
0x0013 (19)	Invalid IO Config
0x0100 (256)	Axis
0x0101 (257)	Axis: axis invalid
0x0102 (258)	Axis: unable to set command position
0x0103 (259)	Axis: not mapped to motion supervisor
0x0200 (512)	Capture
0x0201 (513)	Capture: invalid motor number
0x0202 (514)	Capture: invalid capture type
0x0203 (515)	Capture: invalid capture number
0x0204 (516)	Capture: invalid feedback number
0x0205 (517)	Capture: invalid capture edge
0x0206 (518)	Capture: capture is not enabled
0x0207 (519)	Capture: invalid capture state
0x0208 (520)	Capture: capture not supported by primary feedback
0x0209 (521)	Capture: capture not supported by secondary feedback
0x020a (522)	Capture: capture is already armed
0x0300 (768)	Client
0x0301 (769)	Client: method invalid
0x0302 (770)	Client: header invalid
0x0303 (771)	Client: server MPI version incompatible
0x0304 (772)	Client: server incompatible
0x0305 (773)	Client: server inaccessible

0x0306 (774) Client: server MPI not match bit size
0x0400 (1024) Command
0x0401 (1025) Command: type invalid
0x0500 (1280) Compensator
0x0501 (1281) Compensator: compensator object invalid
0x0502 (1282) Compensator: compensator object not configured
0x0503 (1283) Compensator: object not enabled
0x0504 (1284) Compensator: axis not enabled
0x0505 (1285) Compensator: table size is too small, increase the controller compensatorPointCount
0x0506 (1286) Compensator: position delta invalid
0x0507 (1287) Compensator: table dimension not supported
0x0600 (1536) Control
0x0601 (1537) Control: application is not compatible with MPI DLL
0x0602 (1538) Control: control invalid
0x0603 (1539) Control: control number exceeds maximum limit
0x0604 (1540) Control: type invalid
0x0605 (1541) Control: interrupts disabled
0x0606 (1542) Control: out of internal memory
0x0607 (1543) Control: out of external memory
0x0608 (1544) Control: background task does not have enough time to execute
0x0609 (1545) Control: motorCount is invalid
0x060a (1546) Control: filterCount is invalid
0x060b (1547) Control: axisCount is invalid
0x060c (1548) Control: axisFrameCount is invalid
0x060d (1549) Control: motionCount is invalid
0x060e (1550) Control: mathBlockCount is invalid
0x060f (1551) Control: sequenceCount is invalid
0x0610 (1552) Control: preFilterDelayCount is invalid
0x0611 (1553) Control: recorderCount is invalid
0x0612 (1554) Control: userLimitCount is invalid
0x0613 (1555) Control: compensatorCount is invalid
0x0614 (1556) Control: captureCount is invalid
0x0615 (1557) Control: TxTime is invalid
0x0616 (1558) Control: sample rate must be greater than or equal to 1kHz
0x0617 (1559) Control: sample rate must be less than or equal to 100kHz
0x0618 (1560) Control: cannot configure while axes are running
0x0619 (1561) Control: cannot configure while recorders are running
0x061a (1562) Control: application compiled with invalid packing alignment
0x061b (1563) Control: firmware invalid
0x061c (1564) Control: no firmware found (factory default)
0x061d (1565) Control: firmware version mismatch
0x061e (1566) Control: FPGA hardware socket does not exist
0x061f (1567) Control: SynqNet state is invalid
0x0620 (1568) Control: I/O bit selected is unavailable
0x0621 (1569) Control: object index exceeds object count
0x0622 (1570) Control: object is not valid
0x0623 (1571) Control: flash cannot be saved, SynqNet state must be SYNQ
0x0624 (1572) Control: flash invalid
0x0625 (1573) Control: flash verify error
0x0626 (1574) Control: flash write error
0x0627 (1575) Control: the file is not accessible
0x0628 (1576) Control: buffer too small to hold the required number of characters
0x0629 (1577) Control: events lost
0x062a (1578) Control: compareCount is invalid

0x062b (1579) Control: sample rate cannot be changed
0x062c (1580) Control: flash: qboot0 in QMP too old.
0x062d (1581) Control: flash: qboot0 incompatible with QMP.
0x062e (1582) Control: Failed to stop controller
0x062f (1583) Control: Too many threads
0x0630 (1584) Control: No Client found for thread
0x0631 (1585) Control: Object cannot be used after reallocation
0x0632 (1586) Control: Power-on Self-Test In Progress
0x0633 (1587) Control: Firmware address size mismatch.
0x0700 (1792) driveMap
0x0701 (1793) driveMap: cannot open drive map file
0x0702 (1794) driveMap: format error in drive map file
0x0703 (1795) driveMap: node type not found in drives map files
0x0704 (1796) driveMap: drive firmware version not found in drive map file (see drive vendor for .dm file update)
0x0705 (1797) driveMap: drive parameter is read-only
0x0800 (2048) Element
0x0801 (2049) Element: element invalid
0x0900 (2304) Event
0x0901 (2305) Event: event invalid
0x0a00 (2560) Filter
0x0a01 (2561) Filter: filter invalid
0x0a02 (2562) Filter: filter algorithm invalid
0x0a03 (2563) Filter: dRate value out of range (0-7)
0x0a04 (2564) Filter: divide by zero in conversion
0x0a05 (2565) Filter: postfilter section not enabled
0x0a06 (2566) Filter: invalid filter form
0x0a07 (2567) Filter: smoothing value out of range (0-.999999)
0x0c00 (3072) List
0x0c01 (3073) List: element not found
0x0c02 (3074) List: element invalid
0x0d00 (3328) Map
0x0d01 (3329) Map: name invalid
0x0d02 (3330) Map: name not found
0x0d03 (3331) Map: index invalid
0x0d04 (3332) Map: file invalid
0x0d05 (3333) Map: symbol not found
0x0d06 (3334) Map: symbol invalid
0x0f00 (3840) Motion
0x0f01 (3841) Motion: motion invalid
0x0f02 (3842) Motion: axis count invalid
0x0f03 (3843) Motion: axis frame count invalid
0x0f04 (3844) Motion: type invalid
0x0f05 (3845) Motion: attribute invalid
0x0f06 (3846) Motion: MPIStateIDLE
0x0f07 (3847) Motion: MPIStateMOVING
0x0f08 (3848) Motion: MPIStateSTOPPING
0x0f09 (3849) Motion: MPIStateSTOPPED
0x0f0a (3850) Motion: MPIStateSTOPPING_ERROR
0x0f0b (3851) Motion: MPIStateERROR
0x0f0c (3852) Motion: auto-start
0x0f0d (3853) Motion: illegal delay
0x0f0e (3854) Motion: profile error
0x0f0f (3855) Motion: motion type is not supported by controller

0x0f10 (3856) Motion: path error
0x0f11 (3857) Motion: frame buffer low
0x0f12 (3858) Motion: frame buffer empty
0x0f13 (3859) Motion: frame buffer overrun
0x0f14 (3860) Motion: Cannot modify user move (too many modifies?).
0x0f15 (3861) Motion: mpiUserProfileModify() called too late.
0x0f16 (3862) Motion: RESERVED0
0x0f17 (3863) Motion: RESERVED1
0x0f18 (3864) Motion: RESERVED2
0x0f19 (3865) Motion: no axis mapped
0x0f1a (3866) Motion: bad path data
0x0f1b (3867) Motion: cannot map axis while moving
0x0f1c (3868) Motion: expected axis map does not match actual axis map
0x0f1d (3869) Motion: move cancel failed
0x0f1e (3870) Motion: modify parameters changed to avoid reversal
0x0f1f (3871) Motion: modify could not execute without reversing motion
0x1000 (4096) Motor
0x1001 (4097) Motor: motor invalid
0x1002 (4098) Motor: motor type invalid
0x1003 (4099) Motor: stepper motors are not available
0x1004 (4100) Motor: motor not enabled
0x1005 (4101) Motor: secondary feedback not available
0x1006 (4102) Motor: hardware not found
0x1007 (4103) Motor: cannot set disable action to CMD_EQ_ACT when motor type is STEPPER
0x1008 (4104) Motor: cannot set motor type to STEPPER when disable action is CMD_EQ_ACT
0x1009 (4105) Motor: stepper Pulse Width out of range (.00000006 < pulseWidth < .00100006
0x100a (4106) Motor: cannot reverse the feedback for specified feedback type
0x100b (4107) Motor: motor phase finding failure
0x100c (4108) Motor: Drive faults prevents phase finding
0x100d (4109) Motor: Commutation Error during phase Find
0x100e (4110) Motor: Phase finding abort, MPHASE not active
0x100f (4111) Motor: specified demand mode not supported Motor: specified demand mode not supported by drive
0x1010 (4112) Motor: cannot switch the demand mode while the amplifier is enabled
0x1011 (4113) Motor: position feedback offset storage not supported
0x1012 (4114) Motor: position feedback offset set failed
0x1013 (4115) Motor: position feedback offset data uninitialized or corrupted
0x1100 (4352) Notify
0x1101 (4353) Notify: wait in progress
0x1200 (4608) Packet
0x1201 (4609) Packet: address invalid
0x1202 (4610) Packet: communication error
0x1203 (4611) Packet: connection closed
0x1300 (4864) GeomtricPath
0x1301 (4865) GeomtricPath: dimension out of range
0x1302 (4866) GeomtricPath: illegal element
0x1303 (4867) GeomtricPath: arc dimension out of range
0x1304 (4868) GeomtricPath: illegal radius
0x1305 (4869) GeomtricPath: path too long
0x1306 (4870) GeomtricPath: unsupported interpolation type for this function
0x1307 (4871) GeomtricPathElement: velocity must be positive
0x1308 (4872) GeomtricPathElement: acceleration must be positive
0x1309 (4873) GeomtricPathElement: timeSlice must be greater than 2x the sample period
0x130a (4874) GeomtricPathElement: unsupported planning type

0x130b (4875) GeomtricPathElement: vel/accel time is too long for path section
0x130c (4876) GeomtricPathElement: path length is zero
0x130d (4877) GeomtricPathElement: 2*vel*vel/radius exceeds specified acceleration
0x130e (4878) GeomtricPathElement: radius tolerance must be positive
0x130f (4879) GeomtricPathElement: sample period must be positive
0x1400 (5120) Win64
0x1401 (5121) Win64: platform invalid
0x1402 (5122) Win64: device invalid
0x1403 (5123) Win64: device invalid, XMP not supported by this version of the MPI
0x1404 (5124) Win64: device error
0x1405 (5125) Win64: device map error
0x1406 (5126) Win64: copy64 failure
0x1407 (5127) Win64: controller halted
0x1408 (5128) Win64: no such file or directory
0x1409 (5129) Win64: the path is not a directory
0x140a (5130) Win64: the MPI install directory environment variable is not set
0x140b (5131) Win64: incompatible driver version
0x140c (5132) Platform: invalid file type
0x140d (5133) Platform: incorrect file version
0x140e (5134) Platform: unknown frame type
0x1500 (5376) Recorder
0x1501 (5377) Recorder: already started
0x1502 (5378) Recorder: already stopped
0x1503 (5379) Recorder: not configured
0x1504 (5380) Recorder: no recorders available
0x1505 (5381) Recorder: not enabled
0x1506 (5382) Recorder: cannot configure while running
0x1507 (5383) Recorder: invalid record count allocation
0x1508 (5384) Recorder: recorder is already reserved
0x1509 (5385) Recorder: recorder is not reserved
0x1600 (5632) Sequence
0x1601 (5633) Sequence: sequence invalid
0x1602 (5634) Sequence: command count invalid
0x1603 (5635) Sequence: command not found
0x1604 (5636) Sequence: MPISequenceStateSTARTED
0x1605 (5637) Sequence: MPISequenceStateSTOPPED
0x1700 (5888) Server
0x1701 (5889) Server: method invalid
0x1702 (5890) Server: header invalid
0x1800 (6144) SynqNet
0x1801 (6145) SynqNet: synqNet invalid
0x1802 (6146) SynqNet: node count exceeds the maximum
0x1803 (6147) SynqNet: unexpected network state
0x1804 (6148) SynqNet: network communication is down
0x1805 (6149) SynqNet: network down due to CRC errors
0x1806 (6150) SynqNet: network down due to Rx errors
0x1807 (6151) SynqNet: network down due to Rx packet length errors
0x1808 (6152) SynqNet: network down due to Rx pack errors
0x1809 (6153) SynqNet: network down due to Rx dribble
0x180a (6154) SynqNet: network down due to Rx CRC errors
0x180b (6155) SynqNet: interface not available
0x180c (6156) SynqNet: dynamic memory network topology mismatch, network in ASYNQ state
0x180d (6157) SynqNet: flash memory network topology mismatch, network in ASYNQ state
0x180e (6158) SynqNet: timeout, reset request packet

0x180f (6159) SynqNet: timeout, reset complete packet
0x1810 (6160) SynqNet: timeout, discovery problem
0x1811 (6161) SynqNet: no nodes found on network
0x1812 (6162) SynqNet: no timing data available in module
0x1813 (6163) SynqNet: invalid packet buffer
0x1814 (6164) SynqNet: too many motors configured for this node
0x1815 (6165) SynqNet: invalid auxiliary feedback count
0x1816 (6166) SynqNet: invalid command configuration
0x1817 (6167) SynqNet: invalid pulse engine count
0x1818 (6168) SynqNet: invalid feedback count
0x1819 (6169) SynqNet: invalid capture count
0x181a (6170) SynqNet: invalid ioInput count
0x181b (6171) SynqNet: invalid ioOutput count
0x181c (6172) SynqNet: invalid monitor field configuration
0x181d (6173) SynqNet: invalid analogIn count
0x181e (6174) SynqNet: invalid digitalIn count
0x181f (6175) SynqNet: invalid digitalOut count
0x1820 (6176) SynqNet: invalid analogOut count
0x1821 (6177) SynqNet: cable number is not idle, status is unknown
0x1822 (6178) SynqNet: idle cable number unknown due to failed node(s)
0x1823 (6179) SynqNet: only supported with ring topology
0x1824 (6180) SynqNet: network is currently recovering from a fault
0x1825 (6181) SynqNet: detected an unsupported cable length
0x1826 (6182) SynqNet: cable length measurement timeout
0x1827 (6183) SynqNet: cable length mismatch, network in ASYNQ state
0x1828 (6184) SynqNet: nominal cable length out of range
0x1829 (6185) SynqNet: minimum cable length out of range
0x182a (6186) SynqNet: maximum cable length out of range
0x182b (6187) SynqNet: node FPGA version mismatch warning
0x182c (6188) SynqNet: node specific initialization failed
0x182d (6189) SynqNet: node MAC version mismatch, network in ASYNQ state
0x182e (6190) SynqNet: unrecoverable network scheduling error
0x182f (6191) SynqNet: controller sample rate must be an integer multiple of all node update periods
0x1830 (6192) SynqNet: node control latency maximum exceeded
0x1831 (6193) SynqNet: hot restart, not in SYNQ state
0x1832 (6194) SynqNet: hot restart, recovering
0x1833 (6195) SynqNet: hot restart, test packet active
0x1834 (6196) SynqNet: hot restart, node address assignment failure
0x1835 (6197) SynqNet: hot restart, not all nodes could be restarted
0x1836 (6198) SynqNet: nodes to shutdown must be consecutive
0x1837 (6199) SynqNet: shutdown mask will result in stranded nodes
0x1838 (6200) SynqNet: recovery must be enabled to shutdown nodes
0x1839 (6201) SynqNet: shutdown node mask specifies a node that does not exist
0x183a (6202) SynqNet: node with a boot FPGA is found in the network
0x183b (6203) SynqNet: node FPGA is a lab version (not released for production)
0x183c (6204) SynqNet: node FPGA MAC is a lab version (not released for production)
0x183d (6205) SynqNet: maximum foreground cycle is too long, increase TxTime or reduce controller sample rate
0x183e (6206) SynqNet: downstream packet payload is too large, reduce controller sample rate
0x183f (6207) SynqNet: maximum foreground calculation time exceeds TxTime, increase TxTime or reduce sample rate
0x1840 (6208) SynqNet: invalid compare count
0x1900 (6400) SqNode
0x1901 (6401) SqNode: invalid

0x1902 (6402) SqNode: node invalid
0x1903 (6403) SqNode: unexpected network state
0x1904 (6404) SqNode: config file and network are different
0x1905 (6405) SqNode: map and config files are different
0x1906 (6406) SqNode: not in config file
0x1907 (6407) SqNode: config file format invalid
0x1908 (6408) SqNode: service cmd response timeout
0x1909 (6409) SqNode: node busy, service cmd ready timeout
0x190a (6410) SqNode: service cmd error
0x190b (6411) SqNode: service cmd unsupported
0x190c (6412) SqNode: node specific command is not supported
0x190d (6413) SqNode: node specific discovery failure
0x190e (6414) SqNode: node specific initialization failure
0x190f (6415) SqNode: node type does not match the file provided for download
0x1910 (6416) SqNode: the file provided for download was not found
0x1911 (6417) SqNode: the header information in the download image is invalid
0x1912 (6418) SqNode: node firmware download failed
0x1913 (6419) SqNode: node firmware verify failed
0x1914 (6420) SqNode: firmware download not supported
0x1915 (6421) SqNode: firmware verify not supported
0x1916 (6422) SqNode: boot rom not recognized
0x1917 (6423) SqNode: invalid resource table in node module
0x1918 (6424) SqNode: invalid string length
0x1919 (6425) SqNode: invalid feedback map
0x191a (6426) SqNode: node failure
0x191b (6427) SqNode: exceeded maximum synqnet packet limit
0x191c (6428) SqNode: I/O Module Incompatibility
0x191d (6429) SqNode: I/O Module EEPROM not programmed
0x191e (6430) SqNode: I/O Module Count Exceeded
0x191f (6431) SqNode: I/O Module length check failed
0x1920 (6432) SqNode: I/O Module 3.3V bus current exceeded
0x1921 (6433) SqNode: I/O Module 24V bus current exceeded
0x1922 (6434) SqNode: I/O Slice initialization fault
0x1923 (6435) SqNode: I/O Slice initialization fault too many slices
0x1924 (6436) SqNode: I/O Slice initialization fault vendor mismatch
0x1925 (6437) SqNode: I/O Slice initialization timeout
0x1926 (6438) SqNode: I/O Slice topology mismatch
0x1927 (6439) SqNode: I/O Slice service receive error
0x1928 (6440) SqNode: I/O Slice service too many char
0x1929 (6441) SqNode: I/O Slice service bus error code
0x192a (6442) SqNode: I/O Slice service unknown fault code
0x192b (6443) SqNode: I/O Slice service resource unavailable
0x192c (6444) SqNode: I/O Slice service not supported
0x192d (6445) SqNode: I/O Slice service invalid attribute value
0x192e (6446) SqNode: I/O Slice service already in mode
0x192f (6447) SqNode: I/O Slice service state conflict
0x1930 (6448) SqNode: I/O Slice service attribute not settable
0x1931 (6449) SqNode: I/O Slice service not enough data
0x1932 (6450) SqNode: I/O Slice service attribute not supported
0x1933 (6451) SqNode: I/O Slice service too much data
0x1934 (6452) SqNode: I/O Slice service object does not exist
0x1935 (6453) SqNode: I/O Slice service invalid parameter
0x1936 (6454) SqNode: I/O Slice service store operation failure
0x1937 (6455) SqNode: I/O Slice service unknown error code

0x1938 (6456) SqNode: I/O Slice service timeout
0x1939 (6457) SqNode: I/O Slice service response format
0x193a (6458) SqNode: I/O Slice eeprom format
0x193b (6459) SqNode: I/O Slice too much IO
0x193c (6460) SqNode: boot file not found or corrupt, kollmorgen_ember.a00 must be in path
0x193d (6461) SqNode: parameter is read only
0x193e (6462) SqNode: SFD motor selected, parameter is locked
0x193f (6463) SqNode: monitor config invalid, index not supported
0x1940 (6464) SqNode: monitor config invalid, address not supported
0x1941 (6465) SqNode: monitor support is not available for this drive
0x1942 (6466) SqNode: commutation initialize failure
0x1943 (6467) SqNode: position clear failure
0x1944 (6468) SqNode: node identification invalid, EEPROM over written
0x1945 (6469) SqNode: drive firmware flash erase failure
0x1946 (6470) SqNode: drive ABS multi-turn read failure
0x1947 (6471) SqNode: position feedback offset data uninitialized or corrupt
0x1948 (6472) SqNode: file CRC error
0x1949 (6473) SqNode: firmware download warning
0x194a (6474) SqNode: UART read character failed
0x194b (6475) SqNode: UART read character timeout
0x194c (6476) SqNode: capture module not supported
0x1a00 (6656) UserLimit
0x1a01 (6657) UserLimit: userLimit invalid
0x1a02 (6658) UserLimit: userLimit number exceeds maximum enabled count
0x1b00 (6912) License
0x1b01 (6913) License: registers are bad or do not match serial number
0x1b02 (6914) License: runtime feature or package is not licensed
0x1b03 (6915) License: axis count exceeds the runtime license quantity
0x1b04 (6916) License: controller is unrestricted (legacy)
0x1b05 (6917) License: runtime license has expired
0x1b06 (6918) License: runtime license is not activated. Please return controller to the factory.
0x1b07 (6919) License: application is not licensed. Please run the appLicenseActivate utility.
0x1c00 (7168) Thread
0x1c01 (7169) Thread: thread is not running
0x1c02 (7170) Thread: thread is currently running
0x1c03 (7171) Thread: thread has not been started
0x1d00 (7424) Compare
0x1d01 (7425) Compare: invalid feedback select
0x1d02 (7426) Compare: invalid output invert
0x1d03 (7427) Compare: invalid compare mode invalid
0x1d04 (7428) Compare: invalid buffer size invalid
0x1d05 (7429) Compare: compare is not enabled
0x1d06 (7430) Compare: Compare point load failed
0x1d07 (7431) Compare: Invalid delta count
0x1d08 (7432) Compare: Invalid direction
0x1e00 (7680) MotionRecipe
0x1e01 (7681) MotionRecipe: ALLOC_EXCEEDS_MEMORY
0x1e02 (7682) MotionRecipe: ALLOC_ALREADY_DONE
0x1e03 (7683) MotionRecipe: NOT_SUPPORTED
0x1e04 (7684) MotionRecipe: COORD_MOVE_NOT_SUPPORTED
0x1e05 (7685) MotionRecipe: BEHAVIOR_INVALID
0x1e06 (7686) MotionRecipe: RECIPE_NOT_DOWNLOADED
0x1e07 (7687) MotionRecipe: RUNTIME_PARAMETERS_LIMIT_EXCEEDED
0x1e08 (7688) MotionRecipe: PROFILE_NOT_DOWNLOADED

0x1e09 (7689) MotionRecipe: HOLD CONFIG NOT DOWNLOADED
0x1e0a (7690) MotionRecipe: MOTION_SUPERVISOR_NUMBER_MISMATCH
0x1e0b (7691) MotionRecipe: CONTROLLER_ERROR
0x1e0c (7692) MotionRecipe: CONTROLLER_ERROR_DMA
0x1e0d (7693) MotionRecipe: CONTROLLER_ERROR_DMA_TIMEOUT
0x1e0e (7694) MotionRecipe: UNEXPECTED
0x1e0f (7695) MotionRecipe: MECHAWARE_CONFIG_SIZE_MISMATCH
0x1e10 (7696) MotionRecipe: Cannot activate recipe while moving
0x1f00 (7936) UserProfile
0x1f01 (7937) UserProfile: This feature is not supported by the firmware.
0x1f02 (7938) UserProfile: Profile Table Buffer has already been allocated.
0x1f03 (7939) UserProfile: Profile Table Buffer has not been allocated.
0x1f04 (7940) UserProfile: Error calculating table size.
0x1f05 (7941) UserProfile: The profile for this move has not been loaded.
0x1f06 (7942) UserProfile: No user profile executing.
0x1f07 (7943) UserProfile: Modify error.
0x1f08 (7944) UserProfile: Too late
0x1f09 (7945) UserProfile: Error in profile table.
0x1f0a (7946) UserProfile: Not enough memory in User Profile Buffer

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